DPSA -2 DIFFERENTIAL PRESSURE CONTROLLER WITH DISPLAY FOR DAMPER ACTUATORS

Mounting and operating instructions





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SAFETY AND PRECAUTIONS

Read all the information, the datasheet, Modbus map, mounting and operating instructions and study the wiring and connection diagram before working with the product. For personal and equipment safety, and for optimum product performance, make sure you entirely understand the contents before installing, using, or maintaining this product.

For safety and licensing (CE) reasons, unauthorised conversion and / or modifications of the product are inadmissible.



temperatures, direct sunlight or vibrations. Long-term exposure to chemical vapours in high concentration can affect the product performance. Make sure the work environment is as dry as possible; avoid condensation.

The product should not be exposed to abnormal conditions, such as extreme

All installations shall comply with local health and safety regulations and local electrical standards and approved codes. This product can only be installed by an engineer or a technician who has expert knowledge of the product and safety precautions.



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Avoid contacts with energised electrical parts. Always disconnect the power supply before connecting, servicing or repairing the product.



Always verify that you apply appropriate power supply to the product and use appropriate wire size and characteristics. Make sure that all the screws and nuts are well tightened and fuses (if any) are fitted well.



Recycling of equipment and packaging should be taken into consideration and these should be disposed of in accordance with local and national legislation / regulations.



In case there are any questions that are not answered, please contact your technical support or consult a professional.



PRODUCT DESCRIPTION

The DPSA -2 series are high resolution differential pressure controllers with display. The integrated PI control with anti-windup function offers the possibility to directly control damper actuators. They are equipped with a fully digital state-of-the-art pressure transducer designed for a wide range of applications. Zero point calibration and Modbus registers reset can be executed via a tact switch. They also feature integrated K-factor and an analogue / modulating output (0–10 VDC / 0–20 mA / 0–100 % PWM). All parameters are accessible via Modbus RTU (3SModbus software or Sensistant).

ARTICLE CODES

Codes	Power supply	lmax	Operating range
DPSAF-1K0 -2	-2 18 24)/DC 100 - 4		0—1.000 Pa
DPSAF-2K0 -2	18—34 VDC	100 mA	0—2.000 Pa
DPSAG-1K0 -2	15-24 VAC /	160 mA /	0—1.000 Pa
DPSAG-2K0 -2	18–34 VDC 80 mA	0—2.000 Pa	

INTENDED AREA OF USE

- Differential pressure, air velocity or volume flow measurement in HVAC applications
- Overpressurizing applications: clean rooms to avoid particle contamination or staircases for fire safety
- Underpressurizing applications: restaurant kitchens and biohazard laboratories
- Volume flow application: ensuring the minimum legal ventilation rate (m³/h) for buildings

TECHNICAL DATA

- 4-digit 7-segment LED display for indicating differential pressure, volume flow and air velocity
- Selectable analogue / modulating output: 0–10 VDC / 0–20 mA / PWM (open collector type):
 - ▶ 0–10 VDC mode: min. load 50 k Ω (R₁ ≥ 50 k Ω)
 - ▶ 0—20 mA mode: max. load 500 Ω (R₁ ≤ 500 Ω)
- ▶ PWM mode: PWM Frequency: 1 kHz, min. load 50 k Ω (R, ≥ 50 k Ω)
- Built-in digital high resolution differential pressure sensor
- Air flow velocity can be measured via Modbus RTU (by using an external PSET-PTX-200 Pitot tube connection set)
- Minimum differential pressure range span: 5 Pa
- Minimum volume flow range span: 10 m³/h
- Minimum air velocity range span: 1 m/s
- Selectable response time: 0,1—10 s
- Implemented K-factor
- Differential pressure, volume flow or air velocity readout via Modbus RTU
- Selectable minimum and maximum operating ranges
- Modbus registers reset function (to factory pre-set values)
- Four LEDs for transmitter status indication
- Modbus RTU communication
- Sensor calibration procedure via tact switch
- Aluminium pressure connection nozzles
- Accuracy: ±2 % of the operating range
- Operating ambient conditions:
 - Temperature: -5–65 °C
- Rel. humidity: < 95 % rH (non-condensing)</p>
- Storage temperature: -20–70 °C

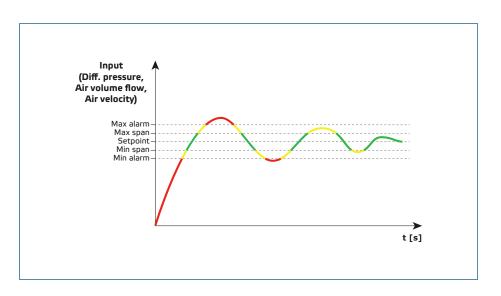


CE

STANDARDS

- Low Voltage Directive 2014/34/EC
 - EN 60529:1991 Degrees of protection provided by enclosures (IP Code) Amendment AC:1993 to EN 60529
 - EN 60730-1:2011 Automatic electrical controls for household and similar use -Part 1: General requirements
- EMC Directive 2014/30/EC
 - EN 60730-1:2011 Automatic electrical controls for household and similar use -Part 1: General requirements
 - EN 61000-6-1:2007 Electromagnetic compatibility (EMC) Part 6-1: Generic standards - Immunity for residential, commercial and light industrial environments
 - EN 61000-6-3:2007 Electromagnetic compatibility (EMC) Part 6-3: Generic standards - Emission standard for residential, commercial and light-industrial environments. Amendments A1:2011 and AC:2012 to EN 61000-6-3
 - EN 61326-1:2013 Electrical equipment for measurement, control and laboratory use - EMC requirements - Part 1: General requirements
 - EN 61326-2-3:2013 Electrical equipment for measurement, control and laboratory use - EMC requirements - Part 2-3: Particular requirements - Test configuration, operational conditions and performance criteria
- WEEE Directive 2012/19/EC
- RoHs Directive 2011/65/EC

OPERATIONAL DIAGRAM





The minimum output value can be adjusted in the range between 0 to 50 %. When the operation mode is 'stop', the damper actuators is driven to the position that corresponds to the minimum output value.



WIRING AND CONNECTIONS

Article type	DPSAF -2	DPSAG -2	
VIN	18—34 VDC	18—34 VDC	15—24 VAC ±10%
GND	Ground	Common ground	AC ~
А	Modbus RTU (RS485), signal A		
/В	Modbus RTU (RS485), signal /B		
A01	Analogue / modulating output (0—10 VDC / 0—20 mA / PWM)		
GND	Ground AO	Common ground	
Connections	Spring contact terminal blocks, cable cross section: 1,5 mm ²		

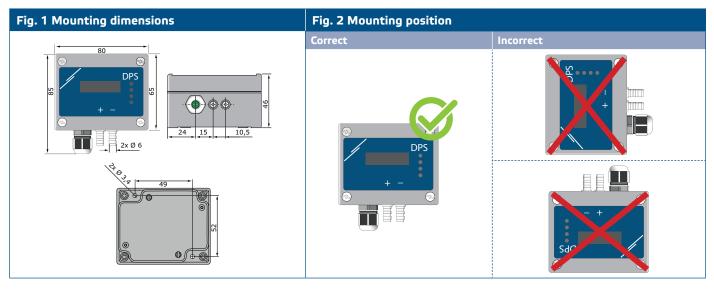


Never connect the common ground of G type articles to other devices powered by a DC voltage. If an AC power supply is used with a unit on a Modbus network, the GND terminal should NOT BE CONNECTED to other units on the network or via the CNVT-USB-RS485 converter. This may cause permanent damage to the communication semiconductors and / or the computer!

MOUNTING INSTRUCTIONS IN STEPS

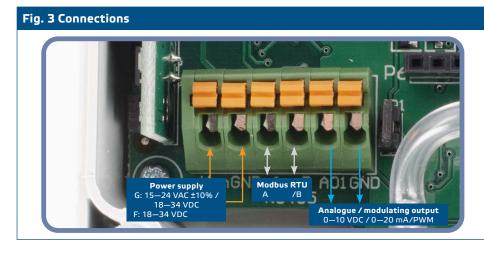
Before you start mounting the unit, read carefully **"Safety and Precautions"**. Choose a smooth surface for installation (a wall, panel, etc.) and follow these steps:

- 1. Unscrew the front cover of the enclosure to remove it.
- Fix the enclosure onto the surface by means of suitable fasteners while adhering to the mounting dimensions shown in Fig. 1 and the correct mounting position shown in Fig. 2 below.

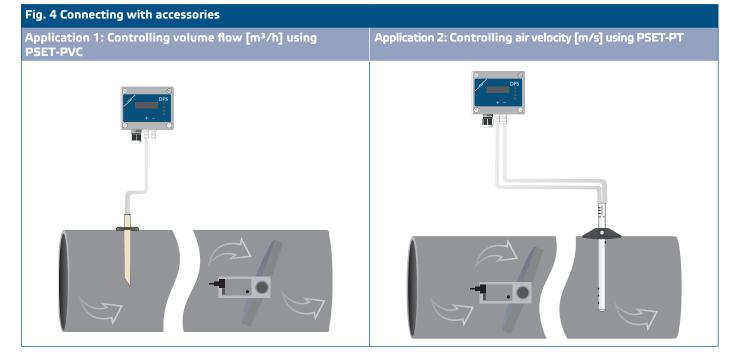


- **3.** Insert the cable into the cable gland.
- Connect as shown in Fig. 3 Connections adhering to the information in section "Wiring and connections".





- **5.** Connect the nozzles to the duct (see **Fig. 4**). Depending the application you must use a specific connection set to connect the nozzles of the unit to the duct:
 - **5.1** To measure differential pressure, use PSET-QF or PSET-PVC set (pressure measurement is the unit default setting);
 - 5.2 To measure volume flow, use PSET-PT Pitot tube connection set, PSET-QF or PSET-PVC connection set. If you use PSET-PT, you should enter the duct cross sectional area [cm²] in Modbus register 63. If you use PSET-QF or PSET-PVC, enter the K-factor of the fan (provided by the fan /motor manufacturer) in Modbus holding register 62. In case the K-factor is not known, volume flow is calculated from a duct cross sectional area (holding register 63) multiplied by air velocity (Pitot air
 - velocity (holding register 64) should be enabled and Pitot tube connected).
 5.3 To measure air velocity, use PSET-PT set and enable Pitot tube air velocity via holding register 64. In this case the K-factor of the fan has to be 0.



6. Connect the nozzles with the tubing.

7. Switch on the power supply.





For sensor calibration and Modbus registers reset procedures, refer to section "Operating instructions". Always calibrate the sensor before initial use.

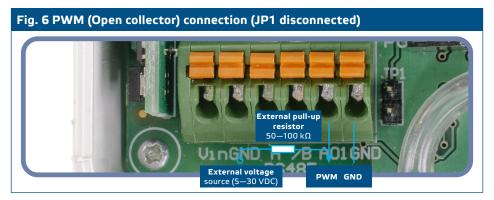
PWM voltage selection:

When the internal pull-up resistor (JP1) is connected , the voltage source is set via Modbus holding register 54, i.e. 3,3 VDC or 12 VDC. See **Fig. 5** *Pull -up resistor jumper connected.*

Fig. 5 Pull-up resistor jumper connected

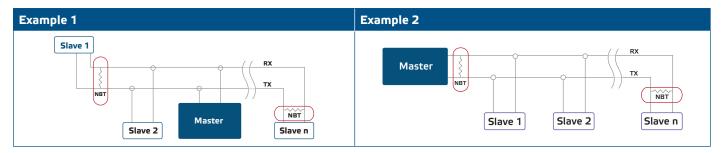


When JP1 is not connected, the output type is Open collector. See Fig. 6. An external pull-up resistor must be used and the analogue output (AO1) must be assigned as PWM output (via holding register 54 - see the *Modbus Map*).



Optional settings

To assure correct communication, the NBT needs to be activated in only two devices on the Modbus RTU network. If necessary, enable the NBT resistor via 3SModbus or Sensistant (*Holding register 9*).





On a Modbus RTU network, two bus terminators (NBTs) need to be activated.

- 8. Put back the front cover and secure it with the screws.
- **9.** Customise the factory settings to the desired ones via the 3SModbus software or the Sensistant configurator. For the default factory settings, see *Modbus register map*.





For the complete Modbus register data, refer to the product Modbus Register Map, which is a separate document attached to the article code on the website and contains the registers list. Products with earlier firmware versions may not be compatible with this list.

OPERATING INSTRUCTIONS

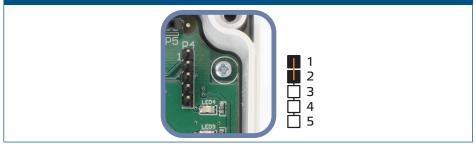
🖹 ΝΟΤΕ		ed information and settings, refer attached to the article code on our	to the product Modbus register map, website.
	 Disconn There ar Either w green Ll (see Fig "C" for c After 2 indicate Make sur Reset of I Press ta printed three tin indicatio The Moc During t 	ED2 and yellow LED3 on the printer . 7 Sensor calibration and Modbus re- calibration will appear on the displa- seconds the green LED2 and yellow that the calibration procedure has re that the nozzles are disconnected Modbus registers procedure: not switch SW1 for 4 seconds until the circuit board blink twice and hold mes (see Fig. 7 Sensor calibration and no). dbus registers are reset to their de	bration process: ess button SW1 for 4 seconds until the d circuit board blink twice and release it egister reset tact switch and indication). ay (see Fig. 8 a Calibration Indication). bw LED3 will blink twice once again to a finished. and unobstructed. the green LED2 and yellow LED3 on the the switch until both LEDs blink again and Modbus register reset tact switch and
Fig. 7 Sensor calibration and Modbus re reset tact switch and indications	egister	Fig. 8 Calibration & Modbus rese	et indication
LED4 LED3 LED2 LED1 SW1		8 a Calibration indication	8 b Modbus reset indication
🖹 NOTE	it until bo both LEDs	oth LEDs blink again three times.	EDs on the PCB blink twice and hold If the tact switch is released before for will have carried out a calibration procedure.

Communication holding registers reset procedure:

 Put the jumper onto pins 1 and 2 of the P4 connector for more than 20 s while the device is powered (see Fig. 9).



Fig. 9 Modbus holding register reset jumper



- **2.** Modbus communication holding registers from 1 to 3 will be reset to the default values.
- **3.** Remove the jumper.

Correct reading of air velocity is possible only if it is enabled by holding register 64 (Pitot air velocity) and a transmitter is connected to the appropriate Pitot tube connection set (PSET-PTX-200).

Differential pressure, volume flow and air velocity mode indications:

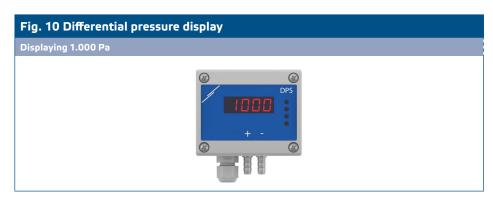
The display is enabled via writing "1" in holding register 91 (Measurement readout). Writing "0" will disable the display.

When the display is enabled, its mode depends on the value in holding register 61 (Operating mode). There are three display modes activated via writing the relevant figure in holding register 61 - see the table below:

Measurement readout enabled		
Value of holding register 61:	Display mode:	
1	Differential pressure	
2	Volume flow rate	
3	Air velocity	

1. Differential pressure display mode:

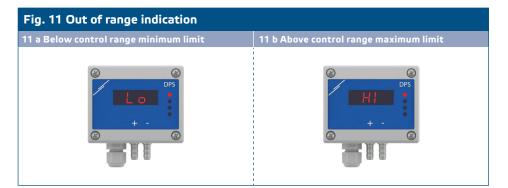
1.1 The LED display indicates the differential pressure level with a resolution of 1 Pa. See **Fig. 10** below. However, since the unit can display up to 4 digits, the values shown are from 0 to 9.999, i.e. if the measured differential pressure = 10.000 Pa, the device displays 9.999. However, the 3SModbus software always indicates the actual value.



- **1.2** Out of range indication:
 - The display shows "Lo" every 3 seconds in case the measured differential pressure is lower than the minimum limit of the control range (see Fig. 11 a).
 - In case the measured differential pressure is higher than the control range maximum limit, the display shows 'HI' every 3 seconds (see Fig. 11 b).

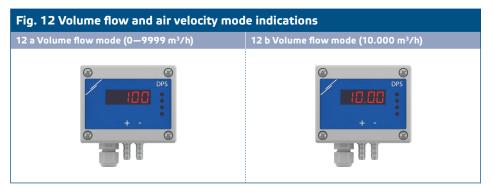






2. Air volume flow display mode:

- 2.1 Air volume flow rate within the range 0—9999 m³/h is displayed with a resolution of 1 m³/h. An example of displaying 100 m³/h is given in Fig. 13 a below.
- **2.2** Air volume flow rate above 10.000 m³/h is displayed divided by 1.000. An example of displaying 10.000 m³/h is given in **Fig. 13 b** below.



3. Air velocity display mode:

3.1 Air velocity is displayed with a resolution of 0,1 m/s. An example of displaying 1,0 m/s is given in **Fig. 13** below.





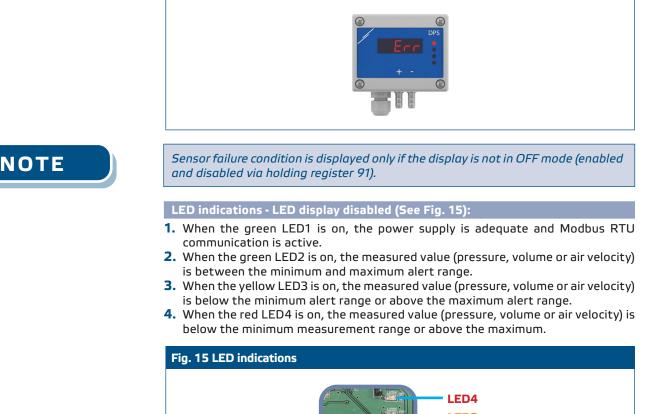
Correct reading of air velocity is possible only if it is enabled by holding register 64 (Pitot air velocity) and a transmitter is connected to the appropriate Pitot tube connection set (PSET-PTX-200).

4. Sensor element failure indication:

In case of failure of sensor element or loss of communication with it, an 'Err' message is displayed and the red LED4 blinks. See **Fig. 14.**



Fig. 14 Sensor element error





Green LED intensity can be adjusted between 0 and 100 % with a step of 10 % according to the value set in Holding register 95.

Kp and Ti tune:

To optimise the functionality of this controller, its behaviour and reaction times must correspond to your application. Optimisation can be done by adjusting the Kp (proportional gain) and Ti (integration time) parameters. If you have extensive knowledge of PI control, you can change Kp and Ti parameters by writing in Modbus Holding Registers 57 and 58.

VERIFICATION OF THE INSTALLATION INSTRUCTIONS

Continuous green LED1 indication as shown in **Fig.16** *Power / Modbus communication indication* means the unit is supplied. If LED1 is not on, check the connections again.

Blinking green LED1 indication as shown in **Fig. 16** *Power / Modbus communication indication* means the unit has detected a Modbus network. If LED1 does not blink, check the connections again.



ΝΟΤΕ

For more information, click here to refer to the product datasheet - Settings.

www.sentera.eu



Fig. 16 Power / Modbus communication indication





The status of the LEDs can be checked only when the unit is energised. Take the relevant safety measures!

TRANSPORT AND STORAGE

Avoid shocks and extreme conditions; stock in original packing.

WARRANTY AND RESTRICTIONS

Two years from the delivery date against defects in manufacturing. Any modifications or alterations to the product after the date of publication relieve the manufacturer of any responsibilities. The manufacturer bears no responsibility for any misprints or mistakes in this data.

MAINTENANCE

In normal conditions this product is maintenance-free. If soiled, clean with a dry or damp cloth. In case of heavy pollution, clean with a non-aggressive product. In these circumstances the unit should be disconnected from the supply. Pay attention that no fluids enter the unit. Only reconnect it to the supply when it is completely dry.