

DPS-M -2 | DIFFERENTIAL PRESSURE TRANSMITTER

Modbus register map



MODBUS REGISTER MAP

| INPUT REGISTERS | | Data type | Description | Raw data range | Values |
|-----------------|---|------------------|--|--|--|
| 1 | Differential pressure | unsigned integer | Measured differential pressure | DPS-M-1K0-2 = 0—1.000 DPS-M-2K0-2 = 0—2.000 DPS-M-4K0-2 = 0—4.000 DPS-M-10K-2 = 0—10.000 | 100 = 100 Pa |
| 2 | Volume flow rate high | unsigned integer | Air Volume flow rate in m ³ /h. Input register 2 contains high significant word, while Input register 3 contains low significant word of Volume flow rate. The value in this registers is equal to the K-factor (holding register 62) of the motor / fan multiplied by square root of measured differential pressure. If K-factor is not known, volume flow rate is calculated from a duct cross sectional area (holding register 63) multiplied by air flow velocity (Pitot air velocity (holding register 64) should be enabled and Pitot tube connected) | DPS-M-1K0-2 = 0—25.000 DPS-M-2K0-2 = 0—40.000 DPS-M-4K0-2 = 0—100.000 DPS-M-10K-2 = 0—180.000 | 1.000 = 1.000 m ³ /h |
| 3 | Volume flow rate low | unsigned integer | | | |
| 4 | Air velocity | unsigned integer | Measured air velocity. Active only if holding register 64 is set to 1 | 0—300 | 100 = 10,0 m/s |
| 5 | Output | unsigned integer | Output value in percentage | 0—1.000 | 100 = 10,0 % |
| 6—7 | | | Reserved, return 0 | | |
| 8 | Air pressure/ volume/ velocity alert flag | unsigned integer | Flag indicates that measured air pressure, volume or velocity is outside set alert values. Set to '1' when the measured value is outside the pressure, volume or velocity alert values set defined by holding registers 13, 14, 20, 21, 22, 23, 28 and 29. Inactive during start-up (power-up) period defined by holding register 93 | 0, 1 | 0 = Pressure/Volume /Velocity measurement OK 1 = Pressure/Volume /Velocity measurement too low/high |
| 9 | Air pressure/ volume/ velocity range limit flag | unsigned integer | Flag indicates that measured air pressure, volume or velocity is outside set range limit values. Set to '1' when the measured pressure is outside the pressure, volume or velocity limit range values set defined by holding registers 11, 12, 16, 17, 18, 19, 26 and 27. Inactive during start-up (power-up) period defined by holding register 93 | 0, 1 | 0 = Pressure/Volume /Velocity range OK 1 = Pressure/Volume /Velocity range too low/high |
| 10 | | | Reserved, returns 0 | | |
| 11 | Sensor fault | unsigned integer | Indicates a failure in pressure sensor | 0, 1 | 0 = Sensor OK 1 = Sensor Fault (Red LED flashing) |
| 12—20 | | | Reserved, return 0 | | |

| HOLDING REGISTERS | | | | | | |
|-------------------|---|------------------|--|--|---|---|
| | | Data type | Description | Raw data range | Values | Factory default values |
| 1 | Device slave address | unsigned integer | Modbus device address | 1–247 | | 1 |
| 2 | Modbus baud rate | unsigned integer | Modbus communication baud rate | 0–6 | 0 = 4.800 3 = 38.400 6 = 230.400 1 = 9.600 4 = 57.600 2 = 19.200 5 = 115.200 | 2 |
| 3 | Modbus parity check | unsigned integer | Parity check mode | 0 = 8N1 1 = 8E1 2 = 8O1 | 0 = None 1 = Even 2 = Odd | 1 |
| 4 | Device type | unsigned integer | Device type, read only | 1.685–1.688 | DPS-M-1K0-2 = 1.685 DPS-M-2K0-2 = 1.686 DPS-M-4K0-2 = 1.687 DPS-M-10K-2 = 1.688 | |
| 5 | HW version | unsigned integer | Hardware version, read only | XXXX | 0x0100 = HW version 1.00 | |
| 6 | FW version | unsigned integer | Firmware version, read only | XXXX | 0x0210 = FW version 2.10 | |
| 7 | | | Reserved, returns 0 | | | |
| 8 | Modbus safety timeout | unsigned integer | After time with no Modbus communication, outputs are set to 0 | 0–60 | 60 = 60 minutes | 0 |
| 9 | Modbus network resistor termination (NBT) | unsigned integer | Set device as end device of the line / or not by connecting NBT | 0, 1 | 0 = NBT disconnected 1 = NBT connected | 0 |
| 10 | Modbus registers reset | unsigned integer | Resets Modbus Holding registers to default values. When finished this register is automatically reset to '0' | 0, 1 | 0 = Idle 1 = Reset Modbus Registers | 0 |
| 11 | Minimum pressure range | unsigned integer | Minimum pressure range, cannot be set higher than maximum pressure range - (minus) minimum pressure range span (50 Pa) | 0–(Maximum pressure range – 50 Pa) | 10 = 10 Pa | 0 |
| 12 | Maximum pressure range | unsigned integer | Maximum pressure range, cannot be set less than minimum pressure range + (plus) minimum pressure range span (50 Pa) | (Minimum pressure range + 50 Pa) - default | 100 = 100 Pa | DPS-M-1K0-2 = 1.000 DPS-M-2K0-2 = 2.000 DPS-M-4K0-2 = 4.000 DPS-M-10K-2 = 10.000 |

| HOLDING REGISTERS | | | | | | |
|-------------------|--------------------------------|------------------|--|--|-----------------------------------|--|
| | | Data type | Description | Raw data range | Values | Factory default values |
| 13 | Min. pressure alert | unsigned integer | Minimum differential pressure alarm value | Min. pressure range—Max. pressure alarm | 10 = 10 Pa | 0 |
| 14 | Max. pressure alert | unsigned integer | Maximum differential pressure alarm value | Min. pressure alarm—Max. pressure range | 100 = 100 Pa | DPS-M-1K0-2 = 1.000 DPS-M-2K0-2 = 2.000 DPS-M-4K0-2 = 4.000 DPS-M-10K-2 = 10.000 |
| 15 | | | Reserved, returns 0 | | | |
| 16 | Minimum volume flow range high | unsigned integer | Minimum volume flow range, cannot be set higher than maximum volume flow range - (minus) minimum volume flow range span (10 m ³ /h). Air volume flow rate in m ³ /h, holding register 16 contains high significant word, while holding register 17 contains low significant word of minimum volume flow rate range | 0—(Maximum volume flow range - 10 m ³ /h) | 10 = 10 m ³ /h | 0 |
| 17 | Minimum volume flow range low | unsigned integer | | | | |
| 18 | Maximum volume flow range high | unsigned integer | Maximum volume flow range, cannot be set less than minimum volume flow range + (plus) minimum volume flow range span (10 m ³ /h). Air volume flow rate in m ³ /h, holding register 18 contains high significant word, while holding register 19 contains low significant word of maximum volume flow rate range | (Minimum volume flow range + 10 m ³ /h) - default | 20.000 = 20.000 m ³ /h | DPS-M-1K0-2 = 25.000 DPS-M-2K0-2 = 40.000 DPS-M-4K0-2 = 100.000 DPS-M-10K-2 = 180.000 |
| 19 | Maximum volume flow range low | unsigned integer | | | | |
| 20 | Min. volume flow alert high | unsigned integer | Minimum volume flow alarm value. Air volume flow rate in m ³ /h, holding register 20 contains high significant word, while holding register 21 contains low significant word of minimum volume flow rate alert | Min. volume flow range - Max. volume flow alarm | 1.000 = 1.000 m ³ /h | 0 |
| 21 | Min. volume flow alert low | unsigned integer | | | | |
| 22 | Max. volume flow alert high | unsigned integer | Maximum volume flow alarm value. Air volume flow rate in m ³ /h, holding register 22 contains high significant word, while holding register 23 contains low significant word of maximum volume flow rate alert | Min. volume flow alarm - Max. volume flow range | 10.000 = 10.000 m ³ /h | DPS-M-1K0-2 = 25.000 DPS-M-2K0-2 = 40.000 DPS-M-4K0-2 = 100.000 DPS-M-10K-2 = 180.000 |
| 23 | Max. volume flow alert low | unsigned integer | | | | |
| 24–25 | | | Reserved, return 0 | | | |
| 26 | Minimum air velocity range | unsigned integer | Minimum air velocity range, cannot be set higher than maximum air velocity range - (minus) minimum air velocity range span (1 m/s) | 0—(Maximum air velocity range - 1 m/s) | 100 = 10,0 m/s | 0 |

| HOLDING REGISTERS | | | | | | |
|-------------------|--|------------------|---|---|---|------------------------|
| | | Data type | Description | Raw data range | Values | Factory default values |
| 27 | Maximum air velocity range | unsigned integer | Maximum air velocity range, cannot be set less than minimum air velocity range + (plus) minimum air velocity range span (1 m/s) | (Minimum air velocity range + 1 m/s)—300 | 300 = 30,0 m/s | 300 |
| 28 | Min. air velocity alert | unsigned integer | Minimum air velocity alarm value | Min. air velocity range—Max. air velocity alarm | 100 = 10,0 m/s | 0 |
| 29 | Max. air velocity alert | unsigned integer | Maximum air velocity alarm value | Min. velocity alarm—Max. air velocity range | 300 = 30,0 m/s | 300 |
| 30—60 | | | Reserved, return 0 | | | |
| 61 | Operating mode | unsigned integer | Operating mode selection | 1—3 | 1 = Differential Pressure 2 = Volume Flow Rate 3 = Air Velocity | 1 |
| 62 | K-factor | unsigned integer | K factor according to the motor / fan specification | 0—1.000 | | 0 |
| 63 | Duct cross sectional area [cm ²] | unsigned integer | Used for calculation of the Volume Flow Rate when K-factor is not known | 0—32.000 | 0 = not used 100 = 100 cm ² | 0 |
| 64 | Pitot air velocity | unsigned integer | Enables Air Velocity Readout. If '0' air velocity readout is disabled, If '1' air velocity readout is enabled and it is accessible in input register 4. Pitot tube needed (PSET-PTX- 200) | 0, 1 | 0 = Disabled 1 = Enabled | 0 |
| 65—69 | | | Reserved, return 0 | | | |
| 70 | Recalibrate sensor | unsigned integer | Recalibrate sensor | 0, 1 | 0 = Inactive 1 = Active | 0 |
| 71—90 | | | Reserved, return 0 | | | 1 |
| 91 | Measurement readout | unsigned integer | 4-digit measurement indication ON / OFF. | 0, 1 | 0 = LED is OFF 1 = LED is ON | 1 |
| 92 | Altitude | unsigned integer | Current altitude | 0—5.000 | 1.000 = 1.000 m | 0 |

HOLDING REGISTERS

| | | Data type | Description | Raw data range | Values | Factory default values |
|-------|----------------------------|------------------|--|----------------|-----------------------------------|------------------------|
| 93 | Start-up Timer | unsigned integer | Start-up (Power-up) timer before setting alert and range limit flags. During this period the alerts and range limits are not compared with the measured pressure/volume/velocity and alert flag and range limit flag registers will remain '0' for this period | 0—1.000 | 100 = 100 s | 60 s |
| 94 | Display response time | unsigned integer | Display response time selection | 1—100 | 10 = 1,0 s | 10 |
| 95 | LED intensity / brightness | unsigned integer | LED intensity (incrementing with step of 10 %) | 0—10 | 0 = OFF 1 = 10 % 10 = 100 % | 5 |
| 96—98 | | | Reserved, return 0 | | | |
| 99 | Output response time | unsigned integer | Output signal response time selection | 1—100 | 10 = 1,0 s | 1 |
| 100 | | | Reserved, returns 0 | | | |

The free Sentera configuration and monitoring software 3SModbus can be downloaded via: <https://www.sentera.eu/en/3SMCenter>